Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	16915	(point\$3 track\$3) & gimbal\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:16
L2	3207	1 & filter\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ÖFF	2005/01/14 17:16
L3	2790	2 & (bas\$3 platform)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT;	OR	OFF	2005/01/14 17:16
			IBM_TDB			
L4	709	3 & gyro\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:17
L5	164	4 & resolver\$1	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:25
L6	1	5 & (filter\$3 same ouput\$3 same gyro same resolver)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:21
L7	5	5 & (filter\$3 & ouput\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:21
L8	111	5 & azimuth	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:25

L9	82	8 & elevat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:26
L10	63	9 & torque	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:27
L11	62	10 & motor\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OŖ	OFF	2005/01/14 17:29
L12	38	11 & (resolver with (elevation azimuth angle))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:30
L13	39	11 & (resolver with (elevation azimuth angle filter\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:34
L14	2	11 & (resolver with (elevation & azimuth & angle & filter\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:35
S1	29225	((gimbal\$3 track\$3 pay\$4 disturb\$4) same system).ti.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:34
S2	11575	S1 & bas\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:35

S3	9360	"2" & resolver	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:42
S4	1508	S2 & filter\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:37
S5	9360	S3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:36
S6	2584	S3 & filter\$3	US-PGPUB; USPAT;	OR	OFF	2005/01/13 17:42
			USOCR; EPO; JPO;			
			DERWENT; IBM_TDB			
S7	42	S2 & resolver	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:37
S 8	20	S7 & filter\$3	US-PGPUB; USPAT;	OR	OFF	2005/01/13 17:37
	1		USOCR;			
			EPO; JPO; DERWENT; IBM_TDB	e symmetric		
S9	6	S8 & gyro	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:41
S10	248	S1 & gyro	US-PGPUB; USPAT;	OR	OFF	2005/01/13 17:41
			USOCR;		-	
-			EPO; JPO; DERWENT;			
			IBM_TDB			

Γ	T		T	1	I	
S11	19	S10 & resolver	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:10
S12	. 6	S11 & filter\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT;	OR	OFF	2005/01/13 17:42
			IBM_TDB			
S13	13	S11 & motor\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 17:48
S14	43	S1 & (azimuth\$4 near3 gimbal\$3)	US-PGPUB;	OR	OFF	2005/01/13 17:50
)		USPAT;		S	
			USOCR; EPO; JPO;			e de la companya de l
			DERWENT;			
			IBM_TDB			
S15	11	S14 & resolver	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:09
S16	6	S15 & filter\$3 & gyro\$4	US-PGPUB;	OR	OFF	2005/01/13 17:50
			USPAT;		1	
			USOCR; EPO; JPO;	i e enga	· .	
			DERWENT;	a as 1.1		. grandu
			IBM_TDB	4 6 4 2 2 2 2 2		
S17	6	S16 & motor\$3 & elevat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:10
S18	10	S11 & motor\$3 & elevat\$4	US-PGPUB;	OR	OFF	2005/01/13 18:12
			USPAT;		-	
			USOCR; EPO; JPO;			
.•			DERWENT; IBM_TDB			

S19	10	S18 & angl\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:15
S20	3	S1 & gyro\$5 & (resolver near3 (elevat\$4 & azimuth))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:16
S21	2	S20 & filter\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:18
S22	14	"5557285"	US-PGPUB; USPAT; USOCR;	OR	OFF	2005/01/13 18:30
			EPO; JPO; DERWENT; IBM_TDB			
633	00					
S23	89	(robert near2 wong).in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:26
S24	88	(robert near1 wong).in.	US-PGPUB; USPAT;	OR	OFF	2005/01/13 18:27
	. :4		USOCR; EPO; JPO;		The state of the s	
	14		DERWENT; IBM_TDB			
S25	26	(douglas near2 bender).in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/13 18:54
S26	0	S22 & vibrat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 13:51

S27	428	(gimbal\$5 track\$3 (payload\$3 near3 point\$3)) & IRU	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 13:56
S28	48	S27 & gyro	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:07
S29	14	"5557285"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:07
S30	5	S29 & gyro	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:09
S31	0	S27 & (gyro\$5 with pauload\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:09
S32	2	S27 & (gyro\$5 with payload\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:10
S33	1	S32 & gimbal\$5 & azimuth	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:13
S34	0	S33 & platform & resolver\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:12

S35	0	S33 & platform & elevat\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 14:12
S36	1	S33 & filter\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/01/14 17:12